

## REPORT DOCUMENTATION PAGE

Form Approved  
OMB No. 0704-0188

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1. AGENCY USE ONLY (Leave blank)		2. REPORT DATE January 18, 1995		3. REPORT TYPE AND DATES COVERED	
4. TITLE AND SUBTITLE Performance and Robustness of Self-Tuning and Adaptive Algorithms for Identification, Filtering and Control				5. FUNDING NUMBERS	
6. AUTHOR(S) P. R. Kumar					
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) University of Illinois at Urbana-Champaign Coordinated Science Laboratory 1308 W. Main Street Urbana, IL 61801-2307				8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES) U. S. Army Research Office P. O. Box 12211 Research Triangle Park, NC 27709-2211				10. SPONSORING/MONITORING AGENCY REPORT NUMBER	
11. SUPPLEMENTARY NOTES The view, opinions and/or findings contained in this report are those of the author(s) and should not be construed as an official Department of the Army position, policy, or decision, unless so designated by other documentation.					
12a. DISTRIBUTION/AVAILABILITY STATEMENT  Approved for public release; distribution unlimited.				12b. DISTRIBUTION CODE  DTIC SELECTED DEC 04 1995 B	
13. ABSTRACT (Maximum 200 words)  We present the main results obtained by us on the topics of  <ul style="list-style-type: none"> <li>(i) design of adaptive systems</li> <li>(ii) analysis of identification, adaptive filtering and adaptive control algorithms</li> <li>(iii) design and analysis of robustness modifications for adaptive algorithms</li> <li>(iv) development of simulation software</li> <li>(v) analysis of simulated annealing</li> <li>(vi) design and analysis of learning algorithms</li> <li>(vii) design and analysis of queueing networks and scheduling policies</li> </ul> DTIC QUALITY INSPECTED 5					
14. SUBJECT TERMS Adaptive systems, Learning, Simulated Annealing, Queueing networks, Scheduling				15. NUMBER OF PAGES 4	
				16. PRICE CODE	
17. SECURITY CLASSIFICATION OF REPORT UNCLASSIFIED	18. SECURITY CLASSIFICATION OF THIS PAGE UNCLASSIFIED	19. SECURITY CLASSIFICATION OF ABSTRACT UNCLASSIFIED	20. LIMITATION OF ABSTRACT UL		

19951130 018

PERFORMANCE AND ROBUSTNESS OF SELF-TUNING  
AND ADAPTATION ALGORITHMS FOR IDENTIFICATION,  
FILTERING AND CONTROL

FINAL REPORT

P. R. KUMAR

JANUARY 18, 1995

U. S. ARMY RESEARCH OFFICE

DAAL03-91-G-0182

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#### 4A. Statement of Problem Studied

The main problems studied were the following:

- (i) Design of adaptation algorithms for identification, adaptive filtering and control.
- (ii) Analysis of the stability, self-optimality, self-tuning, convergence and robustness of adaptation algorithms.
- (iii) How to automate the simulation of complex systems such as adaptive control systems.
- (iv) Develop a theory of and procedures for learning of functions under noisy observations.
- (v) Study the performance of simulated annealing algorithms for optimization.
- (vi) Study the problem of designing scheduling policies for queueing networks, which are central in the modeling of communication, computer and manufacturing systems.
- (vii) Design of scheduling algorithms.

#### 4B. Summary of the Most Important Results

In [3] we have shown that just parameter projection alone is sufficient to render an adaptive control algorithm robust.

In [4] we have designed algorithms for adaptive active noise cancellation and adaptive feedforward control. We have also established the stability and optimality of these algorithms, which include the long-standing open problem of the output error identification algorithm and adaptive IIR filtering.

In [6] we have developed robust adaptive controllers for time varying plants, and established their performance.

In [9] we have presented the theory of self-tuning and convergence for linear stochastic systems.

In [14,15] we have developed a new approach to learning functions under noisy data. We have developed and analyzed canonical smooth estimators and learning procedures. These methods provide a new approach to selecting a model of appropriate complexity.

In [1] we have analyzed a new adaptive controller inspired by some recent results in learning from experts. The method of analysis is quite different from available techniques in adaptive control.

In [5] we have developed a new approach to automating the simulation of complex discrete-time systems. The motivation here is that currently many sophisticated and complex control algorithms are being proposed, and it would considerably enable the movement of these algorithms into practice if one could easily test out such algorithms simply by typing in the equations as typically provided in a technical paper. We have developed a software package ISIM which achieves this purpose.

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In [22] we have shown that the new class of fluctuation smoothing algorithms developed by us for the efficient scheduling of large re-entrant lines can be regarded as simply trying to alleviate total downstream shortfalls.

In [24] we have proved that these algorithms are stable for reentrant lines in random environments.

In [2] we present our new approach to the stability analysis, performance analysis, and design of queueing networks and scheduling policies. We believe that these results represent a quantum jump in the evolution of the field.

#### 4C. List of All Publications and Technical Reports

1. P. R. Kumar, "An Adaptive Controller Based on Learning from Experts," in *Adaptive Control, Filtering, and Signal Processing*, vol. 74, IMA Volumes in Mathematics and its Applications, K. J. Astrom, G. C. Goodwin, and P. R. Kumar, Editors, Springer-Verlag, New York, 1995, to appear.
2. P. R. Kumar, "Scheduling Queueing Networks: Stability, Performance Analysis and Design," *Stochastic Networks*, IMA Volumes in Mathematics and its Applications, vol. 71, F. P. Kelly and R. William, Editors, Springer-Verlag, New York, 1995, to appear.
3. S. M. Naik, P. R. Kumar, and B. E. Ydstie, "Robust Continuous Time Adaptive Control by Parameter Projection," *IEEE Transactions on Automatic Control*, vol. 37, no. 2, pp. 182-197, February 1992.
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13. J. R. Perkins and P. R. Kumar, "Optimal Control of Pull Manufacturing Systems," submitted to *IEEE Transactions on Automatic Control*, 1994.
14. K. L. Buescher and P. R. Kumar, "Learning by Canonical Smooth Estimation, Part I: Simultaneous Estimation," submitted to *IEEE Transactions on Automatic Control*, 1994.
15. K. L. Buescher and P. R. Kumar, "Learning by Canonical Smooth Estimation, Part II: Learning and Model Complexity," submitted to *IEEE Transactions on Automatic Control*, 1994.
16. H. Jin, J. Ou, and P. R. Kumar, "The Throughput of Closed Queueing Networks: Functional Bounds, Asymptotic Loss, Efficiency, and the Harrison-Wein Conjectures," submitted to *Mathematics of Operations Research*, October 1994.
17. K. L. Buescher and P. R. Kumar, "Relating Simultaneous Learning and Simultaneous Estimation for Classes of Sets over Classes of Probabilities," *Proceedings of the 25th Annual Conference on Information Sciences and Systems*, pp. 108-113, Johns Hopkins University, 1991.
18. S. M. Naik and P. R. Kumar, "Robustness of Extended Least Squares Based Adaptive Control," *Proceedings of the 30th IEEE Conference on Decision and Control*, vol. 1, pp. 754-759, Brighton England, December 1991.
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26. S. M. Naik, "Robust Adaptive Control and Filtering," Ph.D. Thesis, 1992.
27. B. Madan, "Adaptive Active Noise Cancellation," M.S. Thesis, 1993.
28. J. R. Perkins, "Control of Push and Pull Manufacturing Systems," Ph.D. Thesis, 1993.

4D. List of all Participating Scientific Personnel Showing Any Advanced Degrees Earned by Them While Employed on the Project

Prof. P. Kumar  
 Mr. Qing Xu  
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 Dr. Chi Hung Lu, Ph.D.  
 Dr. Sanjeev Naik, Ph.D.  
 Dr. Wei Ren, Ph.D.

5. Report of Inventions

- (i) An adaptive active noise cancellation algorithm system.
- (ii) An automated simulator for complex discrete time systems.

6. Bibliography

See list in 4C.